

ModSim Vorlesung MFB420, Prof. Wallrapp, HM

■ Übung 4/10

■ Nichtlineare Rechnung

$$\dot{h} = 1/\rho \cdot A(m\dot{z} - \rho \cdot AL \cdot \sqrt{2g \cdot h})$$

$$\frac{m\dot{z} - \sqrt{2} \cdot AL \cdot \rho \cdot \sqrt{g \cdot h}}{A \cdot \rho}$$

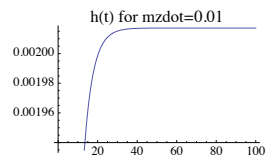
$$\text{par} = \{A \rightarrow 0.12^2 \cdot \pi / 4, AL \rightarrow 0.008^2 \cdot \pi / 4, g \rightarrow 9.81, h_{\max} \rightarrow 0.2, \rho \rightarrow 1000\}$$

$$\{A \rightarrow 0.0113097, AL \rightarrow 0.0000502655, g \rightarrow 9.81, h_{\max} \rightarrow 0.2, \rho \rightarrow 1000\}$$

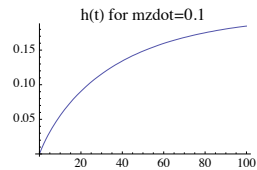
$$h_{\text{dotpar}} = \dot{h} \cdot \text{par}$$

$$0.0884194 \cdot (m\dot{z} - 0.222648 \cdot \sqrt{h})$$

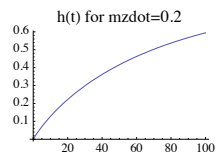
```
erg01 = NDSolve[{h'[t] == hdotpar /. mzd0t -> 0.01, h[0] == 0}, h, {t, 0, 100}];
herg01 = h[t] /. erg01[[1]];
plo01 = Plot[herg01, {t, 0, 100}, PlotLabel -> "h(t) for mzd0t=0.01"]
```



```
erg1 = NDSolve[{h'[t] == hdotpar /. mzd0t -> 0.1, h[0] == 0}, h, {t, 0, 100}];
herg1 = h[t] /. erg1[[1]];
plo1 = Plot[herg1, {t, 0, 100}, PlotLabel -> "h(t) for mzd0t=0.1"]
```

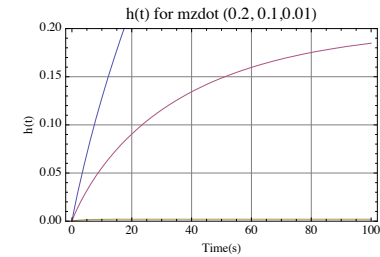


```
erg2 = NDSolve[{h'[t] == hdotpar /. mzd0t -> 0.2, h[0] == 0}, h, {t, 0, 100}];
herg2 = h[t] /. erg2[[1]];
plo2 = Plot[herg2, {t, 0, 100}, PlotLabel -> "h(t) for mzd0t=0.2"]
```



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```
Plot[{herg2, herg1, herg01}, {t, 0, 100}, Frame -> True,
FrameLabel -> {"Time(s)", "h(t)"}, PlotLabel -> "h(t) for mzd0t {0.2, 0.1, 0.01}",
GridLines -> Automatic, PlotRange -> {Automatic, {0, 0.2}}]
```



Achtung: bei mzd0t=0.2 läuft der Tank ueber!

■ Lineare Rechnung mLdot => k h: für h* = 0.1, k = Steigung

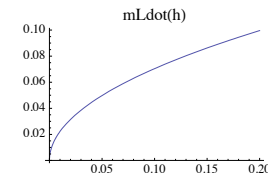
$$m\dot{L}dot = AL \cdot \rho \cdot \sqrt{2g} \cdot \sqrt{h}$$

$$\sqrt{2} \cdot AL \cdot \sqrt{g} \cdot \rho \cdot \sqrt{h}$$

$$m\dot{L}dotpar = m\dot{L}dot \cdot \text{par}$$

$$0.222648 \cdot \sqrt{h}$$

```
plomLdot = Plot[mLdotpar, {h[t], 0, 0.2}, PlotLabel -> "mLdot(h)"]
```



$$dm\dot{L}dot = \text{Simplify}[D[m\dot{L}dot, h[t]]]$$

$$\frac{AL \cdot \sqrt{g} \cdot \rho}{\sqrt{2} \cdot \sqrt{h}}$$

$$k = dm\dot{L}dot \cdot \text{par} \cdot h[t] \rightarrow 0.1$$

$$0.352038$$

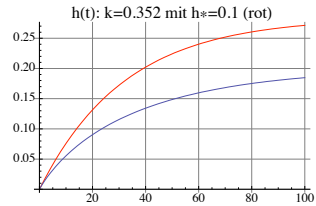
Die Steigung beträgt k = 0.352038

$$dg1 = (h'[t] == m\dot{z}dot / A / \rho - k / A / \rho \cdot h[t]) \cdot \text{par} \cdot m\dot{z}dot \rightarrow 0.1$$

$$h'[t] = 0.00884194 - 0.031127 \cdot h[t]$$

```
erg3lin = NDSolve[{dg1, h[0] == 0}, h, {t, 0, 100}];
herg3lin = h[t] /. erg3lin[[1]];
plo3lin = Plot[herg3lin, {t, 0, 100},
PlotStyle -> {{RGBColor[1, 0, 0]}}, PlotLabel -> "h(t): k=0.352 mit h*=0.1 (rot)"];
```

```
Show[pl03lin, pl01, GridLines -> Automatic]
```



Achtung: diese Linearisierung ($k = 0.352$) liefert grosse Abweichungen bei $h(t)$.

■ Lineare Rechnung mit minimalem Fehler

```
mLdotpar
```

```
0.222648  $\sqrt{h[t]}$ 
```

```
datay = Table[mLdotpar, {h[t], 0, 0.2, 0.01}]
```

```
{0., 0.022648, 0.0314872, 0.0385638, 0.0445297, 0.0497857, 0.0545375,  
0.0589072, 0.0629744, 0.0667945, 0.0704076, 0.0738441, 0.0771276, 0.080277,  
0.0833074, 0.0862313, 0.0890593, 0.0918002, 0.0944617, 0.0970501, 0.0995713}
```

```
datax = Table[0.01 * i, {i, 0, 20}]
```

```
{0, 0.01, 0.02, 0.03, 0.04, 0.05, 0.06, 0.07, 0.08, 0.09,  
0.1, 0.11, 0.12, 0.13, 0.14, 0.15, 0.16, 0.17, 0.18, 0.19, 0.2}
```

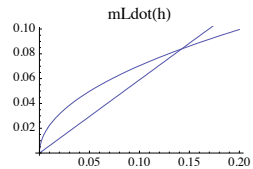
```
data = Transpose[{datax, datay}];
```

```
k = Fit[data, {0, h[t]}, h[t]] / h[t]
```

```
0.590209
```

```
plomLdotlin = Plot[k h[t], {h[t], 0, 0.2}, PlotLabel -> "k(h) "];
```

```
Show[plomLdot, plomLdotlin]
```



```
dgl = (h'[t] == mzdott / A / rho - k / A / rho * h[t]) /. par /. mzdott -> 0.1
```

```
h'[t] == 0.00884194 - 0.052186 h[t]
```

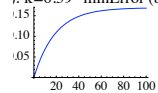
```
erg4lin = NDSolve[{dgl, h[0] == 0}, h, {t, 0, 100}];
```

```
herg4lin = h[t] /. erg4lin[[1]];
```

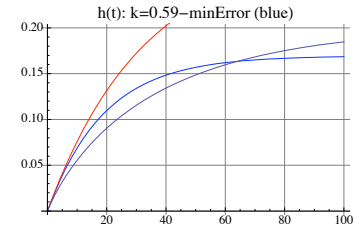
```
pl04lin = Plot[herg4lin, {t, 0, 100},
```

```
PlotStyle -> {{RGBColor[0, 0, 1]}}, PlotLabel -> "h(t): k=0.59-minError (blue)"]
```

```
); k=0.59-minError (bl
```



```
Show[pl04lin, pl03lin, pl01, GridLines -> Automatic, PlotRange -> {Automatic, {0, 0.2}}]
```



Mit dieser linearen Funktion $k = 0.59$ aus minError erhält man eine Lösung, die für die gesamte Höhe brauchbar ist!